Exhibit R-2, RDT&E Budget Item Justification Date: February 2004											
APPROPRIATION/BUDGET ACTIV	/ITY		R-	-1 ITEM							
DEFENSE WIDE RDT&E BA 4			NC	OMENCLATURE	I	PE 0603709	D8Z				
			JO	DINT ROBOTIC	S						
PROGRAM											
COST (\$ in millions)	FY 2003	FY 2004	FY 2005	FY 2006	FY 2007	FY 2008	FY 2009				
Total PE Cost-	19.235	15.784	11.771	11.907	12.145	11.828	12.142				
JOINT SERVICE EOD	3.100	2.500	0.810	0.820	0.840	0.814	0.814				
JAUS	1.000	1.400	0.856	1.086	1.096	1.199	1.357				
GLADIATOR	3.125	1.140	1.140	1.152	1.220	1.090	1.211				
RCSS	2.318	1.058	1.060	1.100	1.120	1.094	1.120				
NUSE 2	0.000	2.100	1.065	1.100	1.123	1.090	1.120				
INTELLIGENT MOBILITY	1.200	1.000	1.120	1.139	1.420	1.261	1.230				
RACS	5.200	4.500	5.520	5.310	5.326	5.280	5.290				
COTS	3.292	2.086	0.200	0.200	0.000	0.000	0.000				

A. Mission Description and Budget Item Justification:

This program is a budget activity level 4 based on the concept/technology development activities ongoing within the program. This PE was established in response to Congressional quidance to consolidate DoD robotic programs on unmanned ground systems and related robotic technologies in order to increase focus of the Services' robotic programs on operational requirements. The program ensures coordination between the Services and provides for interoperability and commonality among unmanned ground systems. The Joint Robotics Program (JRP) will develop and field a family of affordable and effective mobile ground robotic systems; develop and transition technologies necessary to meet evolving user requirements, and serve as a catalyst for insertion of robotic systems and technologies into the force structure. Unmanned Ground Systems are now realizing the often foreseen potential to provide our service men and women with the leap-ahead warfighting capability they need to reduce risk levels to our personnel. The war on terrorism has created urgent and compelling requirements for UGVs. The JRP has responded by deploying unmanned countermine and reconnaissance systems to Bosnia and Kosovo and in support of Operation Enduring Freedom and Operation Iraqi Freedom. The JRP continues to support UGV deployments around the globe providing the Services with unmanned force

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protection and countermine capabilities. Increasing Service UGV demand and positive feedback from users in the field have validated the JRP mission.

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B. Program Change Summary: The Program was transferred by direction of Congress from the Department of the Air Force to the Department of Defense for FY 2004 execution.

	FY 2003	FY 2004	FY 2005
Previous President's Budget	19.943	11.515	11.791
Current FY 2005 President's Budget	19.235	15.784	11.771
Total Adjustments	708	+4.269	020
Congressional program reductions			
Congressional rescissions	708		020
Congressional increases		+4.269	
Reprogrammings			
SBIR/STTR Transfer			

C. Other Program Funding Summary:

Not Applicable

D. Acquisition Strategy:

This program's acquisition strategy continues to maintain two tracks: (1) to develop and field first generation UGVs with current technologies, and (2) pursue advanced technologies critical to semi-autonomous mobility that can be inserted into first generation systems in an evolutionary manner.

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Exhibit R-2a,	e: Februa	ry 2004					
APPROPRIATION/BUDGET ACTI	VITY		R-	·1 ITEM			
DEFENSE WIDE RDT&E BA 4			NC	MENCLATURE		PE 0603709	D8Z
			JC	INT ROBOTIC	S		
			PF	ROGRAM			
COST (\$ in millions)	FY 2003	FY 2004	FY 2005	FY 2006	FY 2007	FY 2008	FY 2009
Joint Service EOD	3.100	2.500	0.810	0.820	0.840	0.814	0.814

A. Mission Description and Budget Item Justification:

This program office is responsible for the lifecycle management of EOD equipment for all four military Services. This particular project will conduct Concept and Technology Development efforts to determine maturity of existing technology and exploration of new concepts to meet EOD requirements. All four Services have the Remote Ordnance Neutralization System (RONS) fielded with their EOD users, and this program includes the RONS Continuous Improvement Program to identify, develop, and qualify improvements to the system. The Joint EOD community has a requirement for a small Man Transportable Robotic System that can conduct EOD tasks to include the use of a manipulator arm to render safe or neutralize unexploded ordnance in confined areas that current systems have difficulty accessing. Also, the Joint EOD community needs increased autonomy in its robotic platforms, and cooperative control of the different classes of robots, and these needs are addressed in this project. The acquisition strategy for Joint Service EOD Robotics includes the conduct of an Analysis of Alternatives by the Joint users, development of a requirements document by the Joint Users, competitive solicitation of a development contract, with built-in options for production, upgrades, support and spare parts. Each Service individually funds for their production, upgrade, support, and spares.

B. Accomplishments/Planned Program

	FY 2003	FY 2004	FY 2005
Accomplishment/Effort/Subtotal	3.100	0.000	0.000
Cost	3.133	0 . 0 0 0	0.000
RDT&E Articles Quantity * (as			
applicable)			

• Took delivery of MTRS Performance Specification Verification Models.

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- Initiated government testing and evaluation of MTRS Performance Specification Verification Models.
- Took delivery of, and evaluated, Semi-Autonomous Remote Ordnance Neutralization System prototype.

	FY 2003	FY 2004	FY 2005
Accomplishment/Effort/Subtotal			
Cost	0.000	2.500	0.810
RDT&E Articles Quantity * (as			
applicable)			

- Order MTRS Production Representative Models and conduct final government testing..
- Achieve Production Decision for the MTRS AAP, and transition to Production Phase for the four Services.
- Initiate block upgrade development in accordance with the MTRS evolutionary acquisition approach.
- Demonstrate improved manipulation capability on prototype Semi-Autonomous RONS.
- Complete RONS Continuous Improvement Program project for PC-based electronics and develop additional Semi-Autonomous RONS capabilities.
- Execute user-prioritized RONS Continuous Improvement projects.

C. Other Program Funding Summary:

Not Applicable

D. Acquisition Strategy:

Not Applicable

E. Major Performers:

Not Applicable

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DEFENSE-WIDE								Date: February 2004						
, and the second								Joint Service	e EOD					
BUDGET ACTIVITY 4				PE 0603709										
ĕ	Contract	Performing		Total	2003	2003	2004	2004	2005	20	05 Co		Total	Target
` · ·	Method &	Activity &			Cost	Award	Cost	Award	Cost	Award	Co	omplete	Cost	Value of
Requirements)	Туре	Location		Cost		Date		Date		Date				Contract
Primary Hardware Development					1.500		1.960		0.250					
Ancilliary Hardware Development														
Systems Engineering					0.210		0.250		0.250					
Licenses														
Tooling														
GFE														
Award Fees														
					1.710		2.210		0.500					
Subtotal Product Development Remarks:					1.710		2.210		0.300					
Subtotal Product Development Remarks:		<u> </u>												
Remarks:					0.100		0.100		0.100		<u> </u>			
Remarks: Development Support											<u> </u>			
Remarks: Development Support Software Development					0.100 0.500		0.100		0.100					
Development Support Software Development Training Development					0.100		0.100		0.100					
Development Support Software Development Training Development Integrated Logistics Support					0.100 0.500		0.100		0.100					
•					0.100 0.500		0.100		0.100					
Development Support Software Development Fraining Development integrated Logistics Support Configuration Management					0.100 0.500		0.100		0.100					

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_	Contract Method & Type	Performing Activity & Location	Total PYs Cost	2003 Cost	Cost		Cost		Cost To Complete		Target Value of Contract
DT				0.100	0.090		0.110				
IOT&E											
Initial Verification Testing											
Subtotal T&E				0.100	0.090		0.110				
Contractor Engineering Support				0.200							
Government Engineering Support Program Management Support			1	0.200							
Program Management Personnel				0.190							
Travel											
Labor (Research Personnel)											
Miscellaneous											
Subtotal Management				0.390	0.000		0.000				
Remarks:		•	•			•				•	•
Total Cost				3.100	2.500		0.810				
Remarks:		•	•	1		1	1	1		•	1

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								E	xhib	it R	-4,	Sche	dule	Pro	file												Da	te: F	ebru	ıary	2004	1				
Appropriation	/Buc	lget .	Acti	vity							Pr	ograi	m El	eme	nt N	umb	er ar	nd N	ame								Pro	oject	Nur	nber	and	Nar	ne			
DEFENSE W	IDE	RD7	Г&Е	/B./	1. #4						PF	E 060	3709	9D8	Z - J	oint	Rob	otics	s Pro	grai	n						Joi	nt S	ervio	e E0	OC					
Eigeel Voor		20	01			20	02			20	003			20	004			20	05			20	06			20	07			20	800			20	09	
Fiscal Year	1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4
MTRS PSVM T&E																																				
MTRS PRM T&E																																				
MTRS AAP PROD DEC																																				
RONS CIP																																				

R-4 Schedule Profile

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Exhibit R-	Dat	te: February	2004							
Appropriation/Budget Activity DEFENSE WIDE RDT&E/B.A. #4		ject Number nt Service E0								
		FY 2001	FY 2002	FY20	03	FY2004	FY2005	FY2006	FY2007	FY2008
MTRS PSVM T&E				3-4Q		1-2Q				
MTRS PRM T&E						3-4Q	1Q			
MTRS AAP PROD DEC							1Q			
RONS CIP Co						Cont.	Cont.	Cont.		

R-4a Schedule Profile

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Exhibit R-2a, RDT&E Budget Item Justification Date: February 2004										
APPROPRIATION/BUDGET ACTIV	VITY		F	k-1 ITEM						
DEFENSE WIDE RDT&E BA 4			N	IOMENCLATURE		PE 0603709	D8Z			
			J	OINT ROBOTIC	S					
			E	ROGRAM						
COST (\$ in millions)	FY 2003	FY 2004	FY 200	5 FY 2006	FY 2007	FY 2008	FY 2009			
JAUS	1.000	1.400	0.856	1.086	1.096	1.199	1.357			

A. Mission Description and Budget Item Justification:

The intent of this program is to develop common open software architecture to ensure unmanned systems' interoperability and evolution with resultant cost savings. JAUS will specify the interfaces between software modules to allow for rapid technology transfer. Continue to develop JAUS such that it attains clear objectives and maintains a consistent philosophy while promoting JAUS as the domain architecture for Unmanned Systems. We will educate the Unmanned Systems community on JAUS to support acquiring, developing, testing, and manufacturing organizations' incorporation of JAUS into their products and services and pursue the adoption of JAUS as a commercial and military standard.

B. Accomplishments/Planned Program

	FY 2003	FY 2004	FY 2005
Accomplishment/Effort/Subtotal	1.000	0.000	0.000
Cost	1.000	0.000	0.000
RDT&E Articles Quantity * (as			
applicable)			

- Released Version 1.0 and Version 1.1 of the JAUS Strategic Plan.
- Drafted Version 1.0 of the JAUS Compliance Specification.
- Drafted Version 3.0 of the JAUS Domain Model.
- Established a JAUS TCP/UDP port number.
- Released Version 1.5 of the JAUS SOP.
- Conducted four JAUS Working Group meetings.

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	FY 2003	FY 2004	FY 2005
Accomplishment/Effort/Subtotal Cost	0.000	1.400	0.856
RDT&E Articles Quantity * (as applicable)			

- Plans for FY2004-2005 are to demonstrate and validate dynamic registration and expansion port capabilities.
- The compliance suite will be completed.
- Establish JAUS as a commercial standard with the Society of Automotive Engineers.
- Release Version 3.0 of the Domain Model.
- Release Version 1.0 of the Compliance Specification.

C. Other Program Funding Summary:

Not Applicable

D. Acquisition Strategy:

Not Applicable

E. Major Performers:

Not Applicable

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Exhibit R-3 Cost Analysis (page 1					Date:	February	2004					
DEFENSE-WIDE			Program Elemen	t			JAUS					
BUDGET ACTIVITY 4			PE 0603709	D8Z								
Cost Categories (Tailor to WBS, or System/Item Requirements)	Contract Method & Type	Performing Activity & Location	Total 2003 Cost	2004 Cost	2004 Award Date	2005 Cost	2005 Award Date	Cost	Award Date	Cost To Complete	Total Cost	Target Value of Contract
Primary Hardware Development												
Ancilliary Hardware Development												
Systems Engineering												
Licenses												
Γooling												
GFE												
Award Fees												
Subtotal Product Developmen	nt											
Development Support												
Software Development			0.65	0 0.75	0	0.50	0					
•									1	ı		_
Γraining Development												
Training Development												
Fraining Development ntegrated Logistics Support												
Training Development Integrated Logistics Support Configuration Management												

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DEFENSE-WIDE BUDGET ACTIVITY 4 Cost Categories Con			Decomons Elomont				Date: February 2004 JAUS					
			Program Element	_			JAUS					
Cost Categories Cor			PE 0603709D8	3Z								
cost categories	ntract	Performing	Total	2004	2004	2005	2005			Cost To	Total	Target
Tailor to WBS, or System/Item Me	thod &	Activity &	2003	Cost	Award	Cost	Award	Cost	Award	Complete	Cost	Value of
Requirements) Typ	e	Location	Cost		Date		Date		Date			Contract
TOT												
OT&E												
Initial Verification Testing	on Testing			0.300)	0.100)					
Subtotal T&E				0.300)	0.100						
Remarks:												
							<u> </u>					
Contractor Engineering Support												
Contractor Engineering Support Government Engineering Support			0.150	0.150		0.056						
Contractor Engineering Support Government Engineering Support Program Management Support			0.150		1	0.056						
Contractor Engineering Support Government Engineering Support Program Management Support Program Management Personnel				0.050)	+						
Contractor Engineering Support Government Engineering Support Program Management Support Program Management Personnel Gravel			0.050	0.050)	0.050						
Contractor Engineering Support Government Engineering Support Program Management Support Program Management Personnel Gravel Labor (Research Personnel) Miscellaneous			0.050	0.050		0.050						

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							I	Exhi	bit	R-4	, Sc	hed	ule	Pro	file												D	ate:	Feb	ruai	y 20	004				
Appropriation/B														Elen													Pı	roje	et N	umb	er a	nd l	Vam	.e		
DEFENSE WID	ER	DT	&E/	B.A	۷. #۷	1					PE	E 06	037	09D	8Z -	– Jo	int l	Rob	otic	s Pr	ogra	am					JA	AUS	,							
Fiscal Year		20	01			20	002			20	003			20	04			20	05			20	006			20	007			20	800			20	09	
riscai i eai	1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4
Acquisition Milestones															,	V 3.:	2																			
Reference Architecture Specification													,	3.1			v	4.0	Ž	.1																
Domain Model												4		V.3.	1	7 .3		V 4.	1	V 1	.3															
Compliance Spec Versions												V 3	3.0		3.2		V 4.		V 4.	.2																
Developmental Evaluation															1.0		V 2.	V .																		

R-4 Schedule Profile

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Exhibit R-4	la, Schedule De	tail		Date: February 2004							
Appropriation/Budget Activity DEFENSE WIDE RDT&E/B.A. #4	Program El PE 0603708	ement Num DZ Joint Ro			Project Number and Name JAUS						
Schedule Profile		FY 2001	FY 2002	FY2003	3 FY2004	FY2005	FY2006	FY2007	FY2008		
RA Versions 3.1; 3.2; 4.0; 4.1		11 2001 11 2002 1			2Q;4Q	1Q; 3Q					
DM Versions 3.0; 3.1; 3.2; 3.3; 4.0; 4	1; 4.2; 4.3				1Q; 2Q; 1Q; 2Q; 3Q; 4Q 3Q; 4Q						
Compliance Spec Versions 1.0; 2.0	liance Spec Versions 1.0; 2.0										
Developmental Evaluation Cont. Cont. Cont.											

R-4a Schedule Profile

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Exhibit R-2a,	RDT&E Bud	get Item J	ustificat	ion	Dat	e: Februar	y 2004
APPROPRIATION/BUDGET ACTI	VITY		R-1	l ITEM			
DEFENSE WIDE RDT&E BA 4			NOI	MENCLATURE		PE 0603709	D8Z
			JO:	INT ROBOTIC	S		
			PRO	OGRAM			
COST (\$ in millions)	FY 2003	FY 2004	FY 2005	FY 2006	FY 2007	FY 2008	FY 2009
GLADIATOR	3.125	1.140	1.140	1.152	1.220	1.090	1.211

A. Mission Description and Budget Item Justification:

The Gladiator Program is a USMC initiative based on the Joint Army-Marine Corps Tactical Unmanned Vehicle (TUV) ORD originated by the U.S. Army Infantry School. Mission Need Statement (MNS) INT 12.1.1 (dated 4 November 1993) validated the need for a tactical unmanned ground vehicle system, and the ORD was approved by the Army in August 1995 and by the Marine Corps in May 1996. Changes in Service deficiencies and required capabilities have led both Services to reevaluate the existing ORD and to initiate efforts to revise it or to approve new requirements documents for robotic systems supporting the tactical commander. The Marine Corps has drafted the Gladiator ORD to support the dismounted infantry of the Marine Ground Combat Element (GCE) with the organic unmanned capability to remote combat tasks including scout/surveillance. The system will reduce risk and neutralize threats to Marines across the full spectrum of conflict and military operations. Gladiator formal requirement document is in final staffing within the Marine Corps. The Gladiator is a teleoperated/semi-autonomous, small-to-medium sized, highly mobile UGV with, initially, the basic capability to conduct scout/surveillance missions and to carry various mission payloads for specific tasks. It will be inherently simple, durable, multi-functional, and easily transported. In the conduct of Operational Maneuver From The Sea (OMFTS), Ship To Objective Maneuver (STOM), Sustained Operations Ashore (SOA), and Operations Other Than War (OOTW), the Gladiator will enhance the ability to accomplish assigned missions. Operating just forward of the GCE units, Gladiator will perform basic scouting/surveillance, obstacle breaching, and NBC reconnaissance tasks while permitting the operator to remain covered or concealed. The basic Marine Corps system will consist of a mobile base unit (MBU), an OCU, and specific mission payload modules (MPMs). Initial MPMs will include Joint Chemical Agent

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Detector (JCAD), Anti-Personnel Obstacle Breaching System (APOBS), and direct fire (lethal and non-lethal) weapons.

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B. Accomplishments/Planned Program

	FY 2003	FY 2004	FY 2005
Accomplishment/Effort/Subtotal Cost	3.125	0.000	0.000
RDT&E Articles Quantity * (as applicable)			

- Complete Technical Development Model (TDM) evaluation and down-select to two contractors.
- Integrate NBC module on Concept Validation Models (CVMs).
- Complete early user evaluation of CVMs.
- Coordinate Gladiator requirements and program plans with the Future Combat System Program.

	FY 2003	FY 2004	FY 2005
Accomplishment/Effort/Subtotal Cost	0.000	1.140	0.000
RDT&E Articles Quantity * (as applicable)			

- Complete Detailed Design of Gladiator.
- Complete Future Naval Capability demonstrations.
- Prepare Milestone B documentation.
- Obtain Milestone B approval, initiate System Design and Development (SDD).

	FY 2003	FY 2004	FY 2005
Accomplishment/Effort/Subtotal	0.000	0.000	1.140
Cost	0.000	0.000	1.140
RDT&E Articles Quantity * (as			
applicable)			

- Complete Log Demo.
- Initiate and complete Development Test.
- Begin Operational Test

C. Other Program Funding Summary:

Gladiator is a cooperative program of the Office of Naval Research and the DoD Joint Robotics Program. The ONR is responsible for funding the major portion of the technology demonstration, while the JRP continues to manage the Gladiator program through SDD to production in support of Marine Corps requirements. FNC funding, under Autonomous Operations is:

FY 2002 5.000 million FY 2003 2.500 million FY 2004 1.500 million

D. Acquisition Strategy:

Two contractors were selected for down select competition for Gladiator SDD. These two contractors are Lockheed Martin, Bethesda, MD and Carnegie Mellon, Pittsburgh, PA.

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E. Major Performers:

Not Applicable

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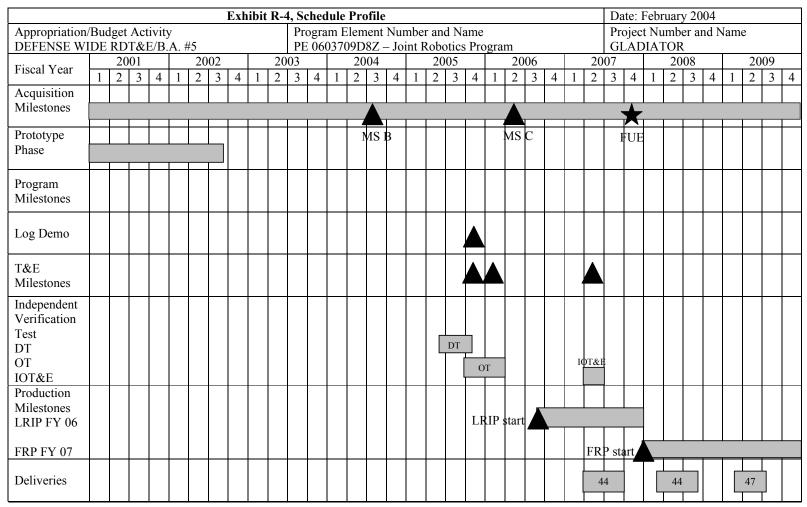
Exhibit R-3 Cost Analysis (page 1)							Date:	February 2	004			
DEFENSE-WIDE BUDGET ACTIVITY 4			Program Ele PE 0603				GLADIA	ATOR				
Cost Categories (Tailor to WBS, or System/Item Requirements)	Contract Method & Type	Performing Activity & Location	Total PYs Cost	2003 Cost	2003 Award Date	Cost	2004 Award Date	2005 Cost	2005 Award Date	Cost To Complete	Total Cost	Target Value of Contract
Primary Hardware Development				2.3	335	1.373	}	0.37	3			
Ancilliary Hardware Development												
Systems Engineering				0.1	148	0.095	i	0.09	5			
Licenses												
Tooling												
GFE												
Award Fees												
Subtotal Product Developn	nent			2.4	183	1.468		0.46	3			
				Ţ		1	T					
Development Support				0.0	040	0.172		0.17	2			
Software Development				0.0	75							
Training Development				0.0)50	0.095	i	0.09	5			
Integrated Logistics Support				0.0)25				1			
Configuration Management				0.0)55							
Technical Data												
GFE									1			
Subtotal Sup	port			0.2	245	0.267	,	0.26	7			

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Remarks:

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Exhibit R-3 Cost Analysis (page 2	2)						Date: February 2004 GLADIATOR					
DEFENSE-WIDE	,		Program Eleme	ent				ΓOR				
BUDGET ACTIVITY 4			PE 060370									
Cost Categories	Contract	Performing	Total	2003	2003	2004	2004	2005	2005	Cost To	Total	Target
	Method &	Activity &	PYs	Cost	Award	Cost	Award	Cost	Award	Complete		Value of
	Type	Location	Cost		Date		Date		Date			Contract
DT												
IOT&E												
Initial Verification Testing				0.13	0	0.135		0.135	5			
Subtotal T&E				0.13	0	0.135		0.135				
Remarks:	l			0.13	U_	0.133		0.13	7	1		
Contractor Engineering Support				0.06	7	0.070		0.070				
Government Engineering Support				0.12		0.120		0.120)			
Program Management Support				0.08		0.080		0.080	_			
Program Management Personnel												
Travel												
Labor (Research Personnel)												
Miscellaneous												
Subtotal Management				0.26	7	0.270		0.270)			
Remarks:												
Total Cost				3.12	5	1.140		1.140)			
Remarks:												



R-4 Schedule Profile

Exhibit R-	4a, Schedule De	tail			Dat	te: February	2004			
Appropriation/Budget Activity Research, Development, Test & Evaluation, Defense-Wide, Budget Activity 4	Program Eleme PE 0603709D8			m		ject Number diator	and Name			
Schedule Profile	•	FY 2001	FY 2002	FY20	003	FY2004	FY2005	FY2006	FY2007	FY2008
Milestone A										
Contract Preparation			1-2Q							
CTD Contract Award			2Q							
CTD			2-4Q	1-4Q						
Milestone B						3Q				
Contract Preparation						2-4Q				
SDD Contract Award						4Q				
SDD						3-4Q	1-4Q			
Developmental Test							3-4Q			
Log Demo							4Q			
Operational Test							4Q	1Q		
Milestone C								2Q		
Low Rate Initial Production								2Q		
IOT&E									2Q	
Full Rate Production									4Q	
First Unit Equipped									4Q	

R-4a Schedule Profile

Exhibit R-2a, RDT&E Budget Item Justification Date: February 2004										
APPROPRIATION/BUDGET ACTIVITY R-1 ITEM NOMENCLATURE										
DEFENSE WIDE RDT&E BA 4			JO	OINT ROBOTICS	PROGRAM	PE 060370	09D8Z			
COST (\$ in millions)	FY 2003	FY 2004	FY 2005	5 FY 2006	FY 2007	FY 2008	FY 2009			
RCSS	2.318	1.058	1.060	1.100	1.120	1.094	1.120			

A. Mission Description and Budget Item Justification:

The Robotic Combat Support System (RCSS) Program is an upgrade approach from the Product Improved Mini-Flail (PIMF). The PIMF has proven effective in Bosnia and Kosovo, as well as in current operation in Afghanistan, as a contingency asset. RCSS threshold requirements include anti-personnel mine clearing and neutralization, improved reliability and human-machine interface, Anti-Personnel wire obstacle breaching, remotely deployed smoke and obscurants, and the capability to carry soldier loads. P3I requirements include advanced controls, remotely delivered special munitions to support dismounted operations, hands-free control using dismounted soldier leader-follower technology, and mechanical devices that will be used to emplace demolitions and special breeching systems. The RCSS Mission Need Statement (MNS) and Operational Requirements Document (ORD) have been approved by Army Training and Doctrine Command (TRADOC).

B. Accomplishments/Planned Program

	FY 2003	FY 2004	FY 2005
Accomplishment/Effort/Subtotal	2.318	0.000	0.000
Cost	2.310	0.000	0.000
RDT&E Articles Quantity * (as			
applicable)			

- Completed evaluation of CTD contract efforts.
- Revised Acquisition Strategy to meet War on Terrorism Urgent Requirements.
- Conducted market survey to determine availability of COTS capability.

	FY 2003	FY 2004	FY 2005
Accomplishment/Effort/Subtotal	0.000	1.055	0.000
Cost		_,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	
RDT&E Articles Quantity * (as			
applicable)			

- Select RCSS COTS vendor.
- Initiate RCSS COTS procurement contract.

- Determine and identify Mission Essential Modules to improve COTS system multi-mission capability.
- Initiate Mission Essential Modules Integration program.

	FY 2003	FY 2004	FY 2005
Accomplishment/Effort/Subtotal Cost	0.000	0.000	1.065
RDT&E Articles Quantity * (as applicable)			

• Continue Mission Essential Module Integration program.

C. Other Program Funding Summary:

Army Procurement funding utilized to procure RCSS COTS systems in FY 04.

D. Acquisition Strategy:

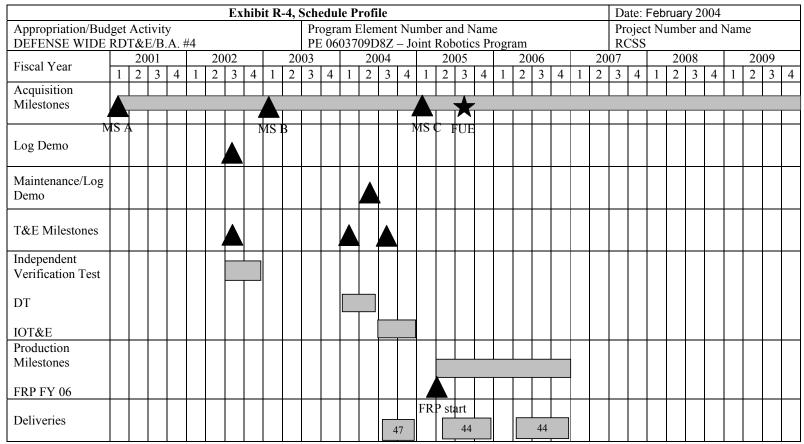
Not Applicable

E. Major Performers:

Not Applicable

DEFENSE-WIDE			Program El	ement			RCSS					
BUDGET ACTIVITY 4			PE 0603	709D8Z								
Cost Categories (Tailor to WBS, or System/Item Requirements)	Contract Method & Type	Performing Activity & Location	Total PYs Cost	Cost	2003 Award Date	Cost	2004 Award Date	Cost	2005 Award Date	Cost To Complete	Total Cost	Target Value of Contract
Primary Hardware Development				1.230		0.284		0.284				
Ancilliary Hardware Development												
systems Engineering				0.446		0.142		0.142	1			
icenses												
Cooling												
GFE												
Award Fees Subtotal Product Development				1.676		0.426		0.426				
Award Fees Subtotal Product Development				1.676		0.426		0.426				
Award Fees Subtotal Product Development Remarks:				0.040		0.426		0.426	ı			
Award Fees Subtotal Product Development Remarks: Development Support												
Subtotal Product Development Remarks: Development Support Software Development				0.040		0.002		0.002				
Subtotal Product Development Remarks: Development Support Software Development Craining Development				0.040 0.075		0.002		0.002				
Subtotal Product Development Remarks: Development Support Software Development Training Development Integrated Logistics Support				0.040 0.075 0.050		0.002 0.062 0.030		0.002 0.062 0.030				
Subtotal Product Development Remarks: Development Support Software Development Training Development Integrated Logistics Support Configuration Management				0.040 0.075 0.050 0.025		0.002 0.062 0.030 0.025		0.002 0.062 0.030				
Subtotal Product Development Remarks: Development Support Software Development Iraining Development Integrated Logistics Support Configuration Management Fechnical Data GFE				0.040 0.075 0.050 0.025		0.002 0.062 0.030 0.025		0.002 0.062 0.030				

Exhibit R-3 Cost Analysis (pag	ge 2)						Date:	February	2004			
DEFENSE-WIDE			Program Elen	nent			RCSS					
BUDGET ACTIVITY 4			PE 06037	09D8Z								
Cost Categories	Contract	Performing	Total	2003	2003	2004	2004	2005	2005	Cost To	Total	Target
(Tailor to WBS, or System/Item	Method &	Activity &	PYs	Cost	Award	Cost	Award	Cost	Award	Complete	Cost	Value of
Requirements)	Туре	Location	Cost		Date		Date		Date			Contract
DT						0.288	3	0.288	3			
IOT&E												
Initial Verification Testing				0.130)							
Subtotal T&I	3			0.130)	0.288	3	0.288	3			
Contractor Engineering Support				0.067	,	0.063		0.065				Т
		1	1			1			1	1	1	- _T
					1	1						+
Government Engineering Support				0.120		0.074		0.074				+
Program Management Support				0.080)	0.063	3	0.065				+
Program Management Personnel Travel												
Labor (Research Personnel)												
Miscellaneous												
Subtotal Managemen	t			0.267	7	0.200)	0.202	2			
Remarks:	·			•	•	•			1			-
Total Cost				2.318	3	1.058	3	1.060)			T
Remarks:												



R-4 Schedule Profile

Exhibit R-	-4a, Schedule De	tail			Da	ite: February	2004			
Appropriation/Budget Activity Research, Development, Test & Evaluation, Defense-Wide, Budget Activity 4	Program Eleme PE 0603709D8			m		oject Number obotic Comba		ystem (RCSS	S)	
Schedule Profile		FY 2001	FY 2002	FY20	03	FY2004	FY2005	FY2006	FY2007	FY2008
Milestone A		1Q								
Contract Preparation		1-4Q	1-4Q	1-4Q						
CTD Contract Award		4Q		1Q						
CTD		4Q	1-4Q	1Q						
Milestone B				1Q						
Contract Preparation			4Q	1Q						
SDD Contract Award				1Q						
SDD				1-4Q						
Developmental Test						1-2Q				
Maintenance/Log Demo						2Q				
IOT&E						3-4Q				
Milestone C							1Q			
Full Rate Production							2Q			
First Unit Equipped							3Q			

R-4a Schedule Profile

Exhibit R-2a,	RDT&E Bud	lget Item J	ustificat:	ion	Date	e: February	y 2004
APPROPRIATION/BUDGET ACTIV	VITY		R-1	ITEM NOME	NCLATURE		
DEFENSE WIDE RDT&E BA 4			JOI	NT ROBOTIC	S PROGRAM	PE 06037	'09D8Z
COST (\$ in millions)	FY 2003	FY 2004	FY 2005	FY 2006	FY 2007	FY 2008	FY 2009
NUSE 2	0.000	2.100	1.065	1.100	1.123	1.090	1.120

A. Mission Description and Budget Item Justification:

The National Unmanned Systems Experimentation Environment (NUSE2) is a new Department of Defense/Private sector teaming initiative. This will be a collaborative effort to provide infrastructure and assets for experimenting with all types of Unmanned Systems - air, ground, surface and underwater - that is national in scope. NUSE2 will provide developers/acquirers of Unmanned Systems with dedicated experimentation facilities, ranges, and airspace that would otherwise be hard to schedule and are often expensive. The initiative will begin in FY 2004, starting with some limited objective experiments using Unmanned Ground Vehicles.

NUSE2 will be a consortium of organizations agreeing to form and provide the experimentation capability. The Nation is the true beneficiary of this effort and conveys the coast-to-coast and Alaska and Hawaii, scope of NUSE2. NUSE2 is intended to provide an experimentation base for Unmanned System acquirers over the life cycle. This will include live as well as virtual experiments. NUSE2 will be a valuable asset in the coming years, providing accessible, affordable, RDTE capabilities. The objectives of NUSE2 are to:

- Assist users in refining capabilities (formerly operational requirements)
- Support acquirers in conducting experiments to reduce technical risk.
- Participate in the evaluation of evolutionary upgrades to Unmanned Systems
- Support experiments associated with Advanced Concept Technology Demonstrations
- Facilitate the evaluation of new technologies and aid the tech transfer process of new capabilities for Unmanned Systems
- Support the developmental, operational, and live fire testing requirements of acquirers
- Aid in the development of advanced integrated architectures as they apply to Unmanned Systems

• Be dual capable, i.e., able to support experimentation and testing in both live and virtual venues

B. Accomplishments/Planned Program

	FY 2003	FY 2004	FY 2005
Accomplishment/Effort/Subtotal Cost	0.000	2.100	0.000
<pre>RDT&E Articles Quantity * (as applicable)</pre>			

- Initiate NUSE2 concept and develop strategy, campaign plan, and organize team.
- Conduct Site Surveys.
- Organize and stand up Integrated Product Teams (IPTs).
- Organize and stand up the Management IPT.
- Identify and refine standards and metrics for experiments.
- Identify and acquire infrastructure requirements.
- Conduct initial live and virtual experiments (countermine).
- Identify and begin planning for follow-on experimentation.

	FY 2003	FY 2004	FY 2005
Accomplishment/Effort/Subtotal Cost	0.000	0.000	1.065
<pre>RDT&E Articles Quantity * (as applicable)</pre>			

- Continue to identify and acquire infrastructure requirements.
- Continue IPT oversight.
- Continue to identify and refine standards and metrics for experiments.
- Conduct live and virtual experimentation.
- Expand NUSE2 as required.
- Expand NUSE2 capabilities to include unmanned air, surface, and subsurface systems.

C. Other Program Funding Summary:

Not Applicable

D. Acquisition Strategy:

Not Applicable

E. Major Performers:

Not Applicable

Exhibit R-3 Cost Analysis (page 1)							Date:	February :	2004			
DEFENSE-WIDE			Program Ele				NUSE 2					
BUDGET ACTIVITY 4		T	PE 0603						1			1
Cost Categories (Tailor to WBS, or System/Item Requirements)	Contract Method & Type	Performing Activity & Location	Total PYs Cost	2003 Cost	2003 Award Date	2004 Cost	2004 Award Date	2005 Cost	2005 Award Date	Cost To Complete	Total Cost	Target Value of Contract
Primary Hardware Development												
Ancilliary Hardware Development												
Systems Engineering												
Licenses												
Γooling												
GFE												
Award Fees Subtotal Product Development	t					0.000	0	0.00	0			
Award Fees Subtotal Product Developmen Remarks:								0.00	0			
Award Fees Subtotal Product Development Remarks: Development Support	t					0.000		0.00	0			
Award Fees Subtotal Product Development Remarks: Development Support Software Development	t							0.00	0			
Award Fees Subtotal Product Development Remarks: Development Support Software Development Training Development								0.00	0			
Award Fees Subtotal Product Development Remarks: Development Support Software Development Fraining Development Integrated Logistics Support								0.00	0			
Award Fees Subtotal Product Development Remarks: Development Support Software Development Fraining Development Integrated Logistics Support Configuration Management								0.00	0			
Subtotal Product Development Remarks: Development Support Software Development Training Development Integrated Logistics Support Configuration Management Technical Data								0.00	0			
Award Fees Subtotal Product Development Remarks: Development Support Software Development Fraining Development Integrated Logistics Support Configuration Management							0	0.00				

Exhibit R-3 Cost Analysis (page 2	2)						Date:	February 2	2004			
DEFENSE-WIDE			Program Elem	nent			NUSE2					
BUDGET ACTIVITY 4			PE 060370	09D8Z								
Cost Categories	Contract	Performing	Total	2003	2003	2004	2004	2005	2005	Cost To	Total	Target
(Tailor to WBS, or System/Item	Method &	Activity &	PYs	Cost	Award	Cost	Award	Cost	Award	Complete	Cost	Value of
Requirements)	Type	Location	Cost		Date		Date		Date			Contract
DT												
ЮТ&Е												
Initial Verification Testing												
0.1170												
Subtotal T&l Remarks:	E											
Contractor Engineering Support	<u> </u>								<u> </u>			
						1.000		0.750				
Government Engineering Support						1.000		0.750				
Government Engineering Support Program Management Support						1.000		0.750				
Government Engineering Support Program Management Support												
Government Engineering Support Program Management Support Program Management Personnel												
Government Engineering Support Program Management Support Program Management Personnel Travel Labor (Research Personnel)												
	nt											
Government Engineering Support Program Management Support Program Management Personnel Travel Labor (Research Personnel) Miscellaneous Subtotal Managemen	nt					0.600						
Government Engineering Support Program Management Support Program Management Personnel Travel Labor (Research Personnel) Miscellaneous	nt					0.600						

								Exl	ıibit	R-	4, S	che	dule	e Pr	ofil	e											Da	ite:	Febi	ruar	y 20	04				
Appropriation											Pr	ogra	am l	Elei	men	t Nu	nbe	er an	d N	ame)						Pr	ojec	t Nı	ımb	er a	nd N	Vam	e		
DEFENSE WI	DE	RD	T&I	E/ B .	A. ŧ	4 4					PE	E 06	037	09I	D8Z	– Jo	int l	Rob	otic	s Pr	ogra	m					NU	JSE	2							
Eigeal Voor		20	01			20	002			20	003			2	004			20	005			20	06			20	07			20	800			20	09	
Fiscal Year	1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4
Infrastructure																																				
Standards Identification																																				
UMS Experiments															4		4																			

R-4 Schedule Profile

Exhibit R	-4a, Schedule De	tail			Dat	e: February	2004			
Appropriation/Budget Activity Research, Development, Test & Evaluation, Defense-Wide, Budget Activity 4	Program Eleme PE 0603709D8.			m		ject Number SE 2	and Name			
Schedule Profile		FY 2001	FY 2002	FY20	03	FY2004	FY2005	FY2006	FY2007	FY2008
Infrastructure						3-4Q	1-4Q			
Standards Identification						3-4Q	1-4Q			
UMS Experiments						3Q	2Q, 4Q			

R-4a Schedule Profile

Exhibit R-2a,	RDT&E Bud	get Item J	ustifi	catio	n	Dat	e: Februar	y 2004				
APPROPRIATION/BUDGET ACTIVITY R-1 ITEM DEFENSE WIDE RDT&E BA 4 NOMENCLATURE PE 0603709D8Z												
DEFENSE WIDE RDT&E BA 4		PE 0603709	D8Z									
				JOINT	T ROBOTIC	S						
				PROGE	RAM							
COST (\$ in millions)	FY 2003	FY 2004	FY 20	005	FY 2006	FY 2007	FY 2008	FY 2009				
Intelligent Mobility Program	1.200	1.000	1.12	20	1.139	1.420	1.261	1.230				

A. Mission Description and Budget Item Justification:

The Intelligent Mobility program is an effort under the U.S. Army Research and Development Command Engineering Center (RDECOM-TARDEC) Intelligent Mobility (IM) Program. Mobility Enhancement through the utilization of novel running gear such as reconfigurable shape, Omni-directional drive systems, and improved mobility sensor integration will improve the mobility of small unmanned ground vehicles (UGVs) to operate on both improved surfaces and off-road terrain in support of urban warfare, physical security and force protection missions for military police and engineering operations. Of particular and immediate interest is the Omni-Directional Inspection System (ODIS) developed through a partnership between the TARDEC robotics mobility lab (TRML) and Utah State University's Center for Self-Organizing and Intelligent Systems (CSOIS), which is a man packable size robot capable of omni-directional locomotion on structured surfaces for the purpose of inspecting vehicles in a force protection role and in an EOD role as an IED disruptor delivery device. There is a current "validated urgent need generated by CENTCOM to utilize UGV's for EOD and force protection missions. Prototype ODIS UGV's are currently in the process of deployment to Iraq and Afghanistan in order to collect data, prove out the current prototype system, and simultaneously provide needed UGV functionality to the user in hostile environments. TRML is also working to develop a draft Mission Needs Statement for the ODIS robot with Military Police/Force Protection agencies.

B. Accomplishments/Planned Program

	FY 2003	FY 2004	FY 2005
Accomplishment/Effort/Subtotal Cost	1.200	0.000	0.000
RDT&E Articles Quantity * (as applicable)			

- Completed successful mission testing at Port of Los Angeles / Port of Long Beach with US Coast Guard and other agencies.
- Supported the Dept. of Justice in a Homeland Defense Force Protection mission during the Lee Malvo Sniper trial
- Extended Other Transaction for follow on ODIS work with Utah State University
- Completed revision and product improvement of ODIS for functional prototype testing.
- Completed build of 10 ODIS systems for extended testing (OCU's are pending 2Q FY 2004)
- Awarded Work Directive for cold regions mechanical testing and RF analysis of small robotic platforms.

	FY 2003	FY 2004	FY 2005
Accomplishment/Effort/Subtotal	0.000	1.000	0.000
Cost		_ , , , ,	
RDT&E Articles Quantity * (as			
applicable)			

	FY 2003	FY 2004	FY 2005
Accomplishment/Effort/Subtotal Cost	0.000	0.000	1.120
RDT&E Articles Quantity * (as applicable)			

FY04 and FY05 expected Accomplishments

- Planned completion of additional 10 ODIS systems for deployment to Iraq, and extended testing (2Q FY 2004)
- Investigate utility and need for ODIS platform variants.
- Improve robot control based on Iraq deployment data
- Improve methods for integrating mission packages
- Investigate other intelligent mobility mechanical concepts for improved functionality

C. Other Program Funding Summary:

\$.800 million awarded to Utah State University using JRP funding previously allocated to US Navy SPAWAR for prototype build of ODIS.

D. Acquisition Strategy:

Not Applicable

E. Major Performers:

Kachemak Research Development Center \$1,995K

Contractor Homer, Alaska

Utah State University \$300K

University Logan, Utah

Utah State University \$800K (reprogrammed funds from US Navy SPAWAR)

University Logan, Utah

	ge 1)						Date:	February	2004			
DEFENSE-WIDE		Prog	gram Elemen	t			Intellige	ent Mobility				
BUDGET ACTIVITY 4			PE 0603	3709D8Z								
	Contract Method &	Performing Activity &	Total PYs	2003 Cost	Award	2004 Cost	2004 Award	2005 Cost	2005 Award	Cost To Complete	Total Cost	Target Value of
Requirements)	Type	Location	Cost		Date		Date		Date			Contract
Primary Hardware Development				0.220		0.223		0.147				
Ancilliary Hardware Development				0.047		0.063		0.049				
Systems Engineering				0.070		0.063		0.033				
Licenses												
Tooling								0.033				
GFE												
Award Fees												
Award Fees Subtotal Product Development Remarks:		†		0.337		0.349		0.262				
Subtotal Product Development Remarks:											<u> </u>	
Subtotal Product Development Remarks: Development Support				0.140		0.063		0.065				
Subtotal Product Development Remarks: Development Support Software Development				0.140 0.187		0.063 0.089		0.065 0.022				
Subtotal Product Development Remarks: Development Support Software Development Training Development				0.140 0.187 0.047		0.063 0.089 0.062		0.065 0.022 0.033				
Subtotal Product Development Remarks: Development Support Software Development Training Development Integrated Logistics Support				0.140 0.187 0.047 0.033		0.063 0.089 0.062 0.032		0.065 0.022 0.033 0.033				
Subtotal Product Development Remarks: Development Support Software Development Training Development Integrated Logistics Support Configuration Management				0.140 0.187 0.047		0.063 0.089 0.062 0.032		0.065 0.022 0.033 0.033 0.065				
Subtotal Product Development Remarks: Development Support Software Development Training Development Integrated Logistics Support Configuration Management Technical Data				0.140 0.187 0.047 0.033		0.063 0.089 0.062 0.032		0.065 0.022 0.033 0.033				
Subtotal Product Development Remarks: Development Support Software Development Training Development Integrated Logistics Support Configuration Management				0.140 0.187 0.047 0.033		0.063 0.089 0.062 0.032		0.065 0.022 0.033 0.033 0.065				

]	Exh	ibit	R -4	l, Sc	hed	lule	Pro	file												Da	ite:	Feb	ruar	y 20	004				
Appropriation/ DEFENSE WI						4										Nuı – Jo						ım								umb t Mo			Vam	ie		
Fiscal Year		20	01			20	002			20	003			20	004			20	05			20	06			20	07			20	80			20	009	
riscai i eai	1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4
Acquisition Milestones																																				
Prototype Phase																																				
ODIS/ODV System Development						A						A																								
ODIS & T-4 System Delivery																									4											
Software Delivery																																				
T&E Milestones																																				

R-4 Schedule Profile

Exhibit R	-4a, Schedule De	etail			Dat	ite: February	2004			
Appropriation/Budget Activity RDT&E, Defense Wide, Budget Activity 4 Program Element Number and Name PE 0603709D8Z Intelligent Mobility										
Schedule Profile		FY 2001	FY 2002	FY20	03	FY2004	FY2005	FY2006	FY2007	FY2008
Contract Preparation		1Q	2Q	1Q		1Q	1Q	1Q	1Q	
System Development		2-4Q	3-4Q	2-4Q		3Q	4Q	3Q	3Q	
Quality Design and Build		4Q	1Q	4Q		4Q	3Q	4Q	4Q	
Developmental (PD&RR) Technical	Testing		4Q	1Q			2Q		4Q	
Developmental Evaluation				1Q			3Q		4Q	
Etc.										

R-4a Schedule Profile

Exhibit R-2a,	RDT&E Bud	get Item J	ustifica	ation	Dat	e: Februar	y 2004				
APPROPRIATION/BUDGET ACTIVITY R-1 ITEM											
DEFENSE WIDE RDT&E BA 4			N	NOMENCLATURE		PE 06037091	D8Z				
			J	JOINT ROBOTIC	S						
			F	PROGRAM							
COST (\$ in millions)	FY 2003	FY 2004	FY 200)5 FY 2006	FY 2007	FY 2008	FY 2009				
RACS	5.200	4.500	5.520	5.310	5.326	5.280	5.290				

A. Mission Description and Budget Item Justification:

The Robotics for Agile Combat Support (RACS) is a USAF effort to advance the robotic state-of-the-art capability for counter-terrorism and force protection technologies. RACS programs include the following: Advancements for the All-purpose Remote Transport System (ARTS), Advanced Systems and Control, Active Range Clearance, Force Protection Robotics, and the Next Generation Explosive Ordnance Disposal Remote Control Vehicle (NGEODRCV). The basic platform for the ARTS has been formally transitioned to a Systems Program Office (SPO) for production and sustainment. Future improvements and advancements will enhance the control and payload capabilities for this system. This technology has been applied to Formerly Used Defense Sites (FUDS) and active range clearance for cleanup/disposal.

B. Accomplishments/Planned Program

	FY 2003	FY 2004	FY 2005
Accomplishment/Effort/Subtotal	5.200	4.500	5.520
Cost	3.200	4.500	3.320
RDT&E Articles Quantity * (as			
applicable)			

• Airborne Engineer - This research effort develop a prototype concept demonstrator that will provide small area ordnance clearance system to allow rapid beddown of RED HORSE personnel. The system includes Power Rake, GPS, New Laptop Operator Control Station, Clam Shell Bucket, and AR-10, 7.62 mm rifle for Stand off Munitions Disruption. The Chief of Staff (CSAF), United States Air Force (USAF) stated that the Air Force requires an Airborne Rapid Engineer Deployable Heavy Operations Repair Squadron, Engineers (RED HORSE) combat engineer capability to "Assess, Prepare and Establish" contingency airbases in remote locations through airdrop, air-insertion, or airdelivery. This requires training some existing RED HORSE personnel as jump-capable and acquiring lighter equipment that is air-droppable, air-insertable, or air-deliverable.

It also requires in some cases for Airborne RED HORSE to be augmented by Explosive Ordnance Disposal (EOD), Readiness, and Fire Rescue to meet mission requirements. This Airborne RED HORSE Engineer Concept of Operations (CONOPS) supports the Global Strike Task Force CONOPS: once F-22 and B-2 stealth roll back the enemy offensive threat and uncover basing structure, follow-on forces in the way of Airborne RED HORSE Engineers can deploy to an air base and fix damaged runways for continued offensive operations. Accomplishments include development and transition of three prototypes of the Airborne Engineer ARTS that were airdrop certified (two of which were deployed to Operation Iraqi Freedom).

- Power Rake This effort is sponsored in cooperation with HQ ACC/CEX for the Air Force Airborne Engineer initiative. The Power Rake is a military munitions clearance tool developed for use on the ARTS robot. The Power Rake will remove or detonate submunitions and anti-personnel mines for the purpose of small area-clearance, lane proofing, and active range clearance. The research goals for this effort are:
 - 1. Investigate the available COTS equipment that is capable of performing this task.
 - 2. Develop and integrate a lightweight armor package for the Power Rake attachment.
 - 3. Characterize the system performance including: explosives resistance, operational capabilities, and system reliability. This effort will provide two proof-of-concept systems for testing and evaluation.
- Enhanced Standoff Munitions Disruption System (E-SMUD) Sponsored in cooperation with the Office of Special Technology EOD Low Intensity Conflict Office, this effort is for EOD personnel of the Air Force and Marines. This research effort consists of integrating a Telepresent Rapid Aiming Platform (TRAP) from Precision Remotes to the ARTS platform to provide EOD personnel the remote capability of detonating, disrupting, or deflagrating small ordnance at safe distances, thereby taking the EOD technician out of harms way. This effort will provide two prototype systems, one for the USMC that incorporates the Barrett .50 caliber and 7.62 mm Designated Marksmanship Rifle (DMR) and another to the USAF with the Barrett .50 caliber and 5.56 mm rifles. These systems provide remote capability to bring to bear 7.62mm or 0.50 caliber rifle against surface scatterable munitions. Integrating visual optics and current pan/tilt technology, this technology removes the EOD technician out-of-harms way to perform clearance of high threat submunitions currently being validated on CONUS ranges while practice for wartime clearance procedures. A low cost laboratory demonstrator version of a AR-10, 7.62mm rifle has been developed and limited testing performed. Transition planned late FY03. Tele-operated Remote Aiming Platform: TRAP is a future P3I effort that is contained in the CE Readiness Modernization Roadmap and is scheduled to undergo system

- design and development (SDD) in FY 2004 with production to follow in FY2005. Accomplishments include demonstration of a radio controlled TRAP system.
- Robo-Trencher US Air Force 738 EIS Initiative to provide a standoff capability to perform cable trenching and excavation in hazardous areas. The system need was prompted by 2 separate UXO incidents with manned equipment. Accomplishments included design, build, testing, and delivery of the Robo-Trencher in 90 Days. The integration of production ARTS robotic components to an existing 738th EIS Ditch Witch 7610 Trenching Tractor demonstrated the feasibility of using ARTS robotics system as a robotic kit. The system is currently deployed to support Operation Enduring Freedom. User is requesting conversion of three more systems including potential spiral development for increased capabilities.
- Automated Ordnance Excavator (AOE) This research effort is to develop technologies that can be integrated into an autonomous excavator. To accomplish this goal, technologies must be developed that address the essential mission elements. The development path for this technology is a four-step process: 1. automated digging, 2. independent boom/stick motion, 3. independent machine mobility, and 4. independent work planning and analysis. A contract has been awarded to Caterpillar, Inc. to develop the 1st stage technology, an Auto-dig Mission Planning Module (AMPM) for the AOE. The AMPM is a JAUS compatible electronics module that will take telemetry data from the AOE, process the data to calculate the boom, stick, and bucket motion paths, and return the motion commands to the AOE for execution. Future efforts will concentrate on the completion of stage 2-4 technologies. Accomplishments for this effort include approximately 75% completion of the auto dig mission planning module and hardware upgrade of the AOE.
- J-LONS (Joint Laser Ordnance Neutralization System) This effort is to develop and validate a remotely operated modular laser system for standoff UXO/IED neutralization capability. Laser technology has been identified as a viable method of clearing areas clear of UXO by rapidly heating the explosive filler to point of detonation. It may also prove to be a method to gain access and disposal to IEDs. Accomplishments include oversight on the international program partner's development of a low power laser system. Commencing in FY 2004, plans are to begin integration of J-LONS onto a mobile unmanned platform.
- Advanced Robotics System The primary effort is to develop common architecture designs for autonomous vehicle technologies that focus on vehicle mobility, speed, and control, as well as multi-vehicle operations and marsupial control. This program seeks to develop and document these modular designs within the evolving JAUS Standards. Specifically the program addresses: (1) vehicle position; (2) sensors; (3) path

- planning; (4) path execution; (5) vehicle control, and (6) obstacle detection and avoidance. Multi-vehicle and marsupial control technologies will be developed. Technologies being investigated are position/mapping (GPS/INS, Dual antenna GPS, dead-reckoning), Advanced Operator Control Unit (laptop/PDA), obstacle detection and avoidance, mobile communications (droppable repeaters) and support for the OSD Joint Architecture for Unmanned Systems (JAUS).
- Accomplishments include support to the JAUS community, obstacle detection and avoidance simulation, sensor fusion for obstacle detection, and high speed assisted tele-operation algorithm development. Demonstrated JAUS concepts by controlling multiple robotic systems using a single operator control station.
- REDCAR (Remote Detection Challenge and Response system) REDCAR is an Air Force, Force Protection Battlelab (AFFB) Initiative to demonstrate the benefits of unmanned systems for the security force mission. The program focuses on the application of mobile unmanned ground systems to support and augment security force personnel in the perimeter defense of Air Force installations and forward deployed units. The AFRL REDCAR system will consist of a network of robotic platforms integrated with existing security force sensors and Tactical, Area Security System (TASS). The REDCAR system will have limited simulation and modeling capabilities to interact with the current AFFPB modeling systems. All components and platforms in the REDCAR system will be capable of communication using JAUS (Joint Architecture for Unmanned Systems) for system interoperability and control. Proof of concepts demonstrations will be conducted in June FY04. Accomplishments development and demonstration of the Scout robotic platform at the Force Protection Battlelab exposition for AF/XOF. Contracts were let for procurement of the MDARS-E and Packbot systems.
- Defense Threat Reduction Agency (DTRA) DTRA's Integrated Technology Demonstration puts to use Department of Defense (DoD) technology and Federal Emergency Management Agency (FEMA) training exercises to provide possible real-world terrorist scenarios. Accomplishment was the CHER-CAP Exercise, which was performed in February 2003 in Northwest Florida. With the close location of many area DoD laboratories and their missions within the DoD, existing priorities and funding were leveraged with the FEMA exercise scenario. The DTRA Combating Terrorism Program will benefit greatly from this opportunity as it will be able to test DoD technologies that are relevant to a variety of threats to DoD forces and assets in the US and abroad. Participating agencies and organizations included: (1) Defense Threat Reduction Agency Technology Directorate (DTRA/TD); (2) Air Force Research Laboratory Airbase Technologies Division (AFRL/MLQ); (3) Naval Coastal Systems Station (CSS); (4) Air Force Civil Engineer Support Agency (AFCESA); (5) Florida State University Panama City (FSU-PC); (6) Local Emergency

Planning Committee, Florida District 1 (LEPC); and (7) Federal Emergency Management Agency (FEMA). Northwest Florida's Comprehensive HAZMAT Emergency Response Capability Assessment Program (CHER-CAP Exercise), demonstrated and integrated the following technologies: (1) Port Occurrence Response Training System (PORTS) for exercise planning and documentation tools; (2) Networked Sensor/C2 System for a deployable sensor network; (3) Common Command and Control for Unmanned Systems for unmanned vehicle/platform utilization; and (4) Underwater Forensic Protocol for Forensic and investigation procedure development.

- STORK The STORK Initiative was a program developed to (1) outfit an Unmanned Aerial Vehicle (UAV) with a communications suite needed to remotely control an Unmanned Ground Vehicle (UGV) and its sensors beyond current system ranges of UGV Ground Control Station; (2) to prove a UAV can deliver a UGV into an area needed during urban operations; and (3) to show UAV/UGV integration can provide persistent target information for Intelligence Preparation of the Battlespace. The STORK Initiative included the following robotic platforms: an ARTS UGV, a Matilda UGV and EEL UGV's, and a Sentry HP UAV. Accomplishments include successful demonstration of the STORK Initiative in March 2003. All objectives were met including extension of UGV control from 2 km out to 26 km, successful insertion of UGV by parachute from the UAV, and simultaneous control of multiple UGV in the area of operations.
- UAV-UGV This program includes: (1) the development of a dual JAUS / NATO STANAGS-compliant UAV to evaluate JAUS viability in the UAV realm, (2) insertion of Aerial Imagery into OCU for map/model building and situational awareness, aerial Communications Relay to extend the radio range of UGVs, (3) precision UGV marsupial emplacement and recovery using a rotary-wing UAV, and (4) an unmanned helicopter to provide aerial pesticide spraying to mitigate vector-borne disease in deployed operations. Accomplishments included the procurement of the rotary-wing UAV and necessary training and transfer of aerial video through JAUS networked system.
- Active Range Clearance The US Army Engineering and Support Center (USAESCH) in Huntsville, Alabama requested the AFRL/MLQF Robotics Group to perform a technology demonstration project for an ongoing clearance operation at the Honey Lake site on Sierra Army Depot, CA. Approximately 2500 acres of Honey Lake were contaminated with military munitions scrap and unexploded ordnance from open pit demolition operations. Accomplishments: AFRL/MLQF Robotics Group used existing robotic equipment and tools to assist in the surface clearance operation at Honey Lake from July through September 2003. AFRL/MLQF used the ARTS robotic system with a Barber Surf Rake to remove the majority of scrap items from the lakebed surface. AFRL/MLQF robotics evaluated several innovative concepts during this demonstration including: Night Operations, Simultaneous

Robotic Operations, and Extended Operations. Robotic night operations were conducted during 6 of the 8 weeks to allow UXO contractor personnel to operate on the site during daylight hours. Multiple systems were simultaneously operated during 2 weeks of the demonstration. In addition, the robotic systems demonstrated the ability to operate in an austere environment for an extended period of time. Over 250 robotic operating hours were accumulated during the technology demonstration. AFRL/MLQF also evaluated a Harley Rock Picker system and towed magnet systems for effectiveness in munitions scrap removal. AFRL's robotic systems removed an estimated 95,600lbs of scrap materials from 19-grids (285 acres) during eight weeks of operations. The site was being cleared using only manual methods by teams of UXO technicians that would walk each grid and pick up all scrap materials larger than a "bottlecap". The robotic system decreased the average time for manual clearance of each grid from 3 weeks to 1 week.

• BomBot - This FY 2004/2005 program investigates low-cost remotely controlled vehicle to deliver an explosive charge to neutralize an Improvised Explosive Device (IED). This will enable a convoy to expediently destroy IEDs remotely through utilization of two alternatives: Non-Recoverable, Recoverable: Non-Recoverable model will be destroyed with the charge and the recoverable model will drop off charge, and then be driven back to the control point. Vehicle is operated using line-of-sight communications.

C. Other Program Funding Summary:

Not Applicable

D. Acquisition Strategy:

Technology transition plans (TTPs) are developed when concept demonstration phases begin. The TTP identifies how and when the technology will transfer from AFRL/MLQ to AAC/YBS (or some other EMD/fielding office). This is the same for every initiative under development. The primary user (typically Air Combat Command) allocates AF POM funding in anticipation/coordination of the TTP for transition to 6.4 and production dollars. Some projects are leveraged with other sponsoring agencies (e.g. Technical Support Working Group) that have their own technology transition office that offers a secondary avenue for an acquisition strategy to reach other federal agencies. A third strategy involves the documentation and drawings that can be offered to industry as a build-to-print option as was the case with the All-purpose Remote Transport System

Air Force Research Laboratory, \$5.200 million Tyndall AFB, Florida

E. Major Performers:

Applied Research Associates Wintec Incorporated University of Florida Titan Corporation

DEFENSE-WIDE BUDGET ACTIVITY 4			Program Ele PE 0603			RACS	3				
Cost Categories Tailor to WBS, or System/Item Requirements)	Contract Method & Type	Performing Activity & Location	Total PYs Cost		2003 2004 Award Cost Date	2004 Award Date	2005 Cost	2005 Award Date	Cost To Complete	Total Cost	Target Value of Contract
Primary Hardware Development				0.870	0.	30	0.610				
Ancilliary Hardware Development				0.370	0.	20	0.640				
Systems Engineering				0.370	0.	20	0.640	D			
Licenses											
Γooling											
GFE											
						30	0.130				
Award Fees				0.130	0.	50	0.13	,			
Subtotal Product Developmen	ıt			1.740			2.030				
Subtotal Product Developmen	ıt			1.740	1.	00	2.030				
Subtotal Product Developmen Remarks: Development Support	t			0.440	0	30	0.270				
Subtotal Product Developmen Remarks: Development Support Software Development	t			0.440 0.440	0	30	0.27(0.27(
Subtotal Product Development Remarks: Development Support Software Development Training Development	ıt			0.440	0	30	0.270				
Development Support Software Development Training Development Integrated Logistics Support	t			0.440 0.440	0	30	0.27(0.27(
Subtotal Product Development Remarks: Development Support Software Development Training Development Integrated Logistics Support Configuration Management	t			0.440 0.440	0	30	0.27(0.27(
Subtotal Product Development Remarks: Development Support Software Development Training Development	t			0.440 0.440	0.0.0.0.0.	30 30 00	0.27(0.27(
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	ge 2)						Date:	February	2004			
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(Tailor to WBS, or System/Item	Method &	Activity &	PYs	Cost	Award	Cost	Award	Cost	Award	Complete	Cost	Value of
Requirements)	Type	Location	Cost		Date		Date		Date			Contract
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IOT&E												
Initial Verification Testing												
		1										
Subtotal T&l	Е			0.480		0.370)	0.320)			
Contractor Engineering Support				0.670		0.110		0.170				
Government Engineering Support				0.250)	0.300)	0.440)			
Government Engineering Support Program Management Support				0.250)	0.300)	0.440)			
Government Engineering Support Program Management Support Program Management Personnel				0.250 0.310 0.230)	0.300 0.520 0.380		0.440)			
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Production																																				

R-4 Schedule Profile

Main Programs in Advancements for ARTS
Remote Water Cutting System
Alternate Control System
Deployed Nozzle
Articulated Remote Manipulation System

Exhibit R-	4a, Schedule De	tail			Da	te: February	2004						
Appropriation/Budget Activity													
Schedule Profile		FY 2001	FY 2002	FY20	03	FY2004	FY2005	FY2006	FY2007	FY2008			
Concept Design		1Q											
Hardware Procurement		2Q											
Quality Design and Build		3Q											
Developmental (PD&RR) Technical	Testing	3Q											
Transition to System Program Office			4Q										
Developmental (User) Evaluation			4Q										
EMD						4Q							
Production								1Q					

Main Programs in Advancements for ARTS
Remote Water Cutting System
Alternate Control System
Deployed Nozzle
Articulated Remote Manipulation System

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Production																													_			_			_				-		

R-4 Schedule Profile

Main Programs within Active Range Clearance
Automated Ordnance Excavator
Remote Standoff Munitions Disruption System
Charge Setting System
Joint Laser Ordnance Neutralization System
Power Rake

Exhibit R-	4a, Schedule De	tail			Dat	te: February	2004			
Appropriation/Budget Activity DEFENSE WIDE RDT&E BA #4	Program Eleme PE 0603709D8			ım		oject Number CS – Active				
Schedule Profile		FY 2001	FY 2002	FY20	03	FY2004	FY2005	FY2006	FY2007	FY2008
Concept Design			1Q							
Hardware Procurement			2Q							
Quality Design and Build				3Q						
Developmental (PD&RR) Technical	Testing			4Q						
Transition to System Program Office						2Q				
Developmental (User) Evaluation						3Q				
EMD								3Q		
Production									3Q	

R-4a Schedule Profile

Main Programs within Active Range Clearance
Automated Ordnance Excavator
Remote Standoff Munitions Disruption System
Charge Setting System
Joint Laser Ordnance Neutralization System
Power Rake

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Prototype Phase																													1													
EMD																																										
Production																																										

R-4 Schedule Profile

Main Programs include
Advanced Navigation capabilities
Object Detection/Avoidance
Multi-vehicle control
Marsupial Control
Path Planning/Execution
JAUS Compliance, Testing, and Evaluation

Exhibit R-	4a, Schedule De	etail			Da	ate: February	2004			
Appropriation/Budget Activity	Program Eleme	ent Number	and Name		Pr	oject Number	and Name			
DEFENSE WIDE RDT&E BA #4	PE 0603709D8	Z Joint Rob	otics Progra	ım	R.A	ACS – Advan	ced Robotic	cs Systems		
Schedule Profile		FY 2001	FY 2002	FY20	003	FY2004	FY2005	FY2006	FY2007	FY2008
Concept Design		1Q								
Hardware Procurement				1Q						
Quality Design and Build							1Q			
Developmental (PD&RR) Technical	Testing								1Q	
Transition to System Program Office										1Q
EMD										1Q
Production										

R-4a Schedule Profile

Main Programs include
 Advanced Navigation capabilities
 Object Detection/Avoidance
 Multi-vehicle control

Marsupial Control
 Path Planning/Execution
 JAUS Compliance, Testing, and Evaluation

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EMD																																				
Production/ Authorization																																		_	_	_

R-4 Schedule Profile

Exhibit R-	4a, Schedule De	etail			Da	te: February	2004			
Appropriation/Budget Activity DEFENSE WIDE RDT&E BA #4	Program Eleme PE 0603709D8			ım	RA	oject Number ACS – Next (mote Contro	Generation I	Explosive O		posal
Schedule Profile	1	FY 2001	FY 2002	FY20		FY2004	FY2005	FY2006	FY2007	FY2008
Concept Design			1Q							
Hardware Procurement				1Q						
Quality Design and Build						1Q				
Developmental (PD&RR) Technical	Testing						1Q			
Transition to System Program Office								4Q		
EMD									1Q	
Production										>>

R-4a Schedule Profile

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Acquisition															_									_					1	_						-	
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Main Programs include

REDCAR DTRA STORK

Exhibit R-	4a, Schedule De	tail			Da	ite: February	2004			
Appropriation/Budget Activity DEFENSE WIDE RDT&E BA #4	Program Eleme PE 0603709D8			ım		oject Number ACS – Force				
Schedule Profile		FY 2001	FY 2002	FY20		FY2004	FY2005	FY2006	FY2007	FY2008
Concept Design			1Q							
Hardware Procurement				3Q						
Quality Design and Build				4Q						
Developmental (PD&RR) Technical	Testing		4Q			1Q				
Transition to System Program Office							4Q			
EMD									3Q	
Production										

R-4a Schedule Profile

Main Programs include REDCAR DTRA STORK

Exhibit R-2a,	RDT&E Bud	lget Item J	Justifica	tion	Dat	e: Februar	y 2004							
APPROPRIATION/BUDGET ACTIVITY R-1 ITEM														
DEFENSE WIDE RDT&E BA 4	PE 0603709	D8Z												
		JO	JOINT ROBOTICS											
		PI	PROGRAM											
COST (\$ in millions)	FY 2003	FY 2004	FY 2005	FY 2006	FY 2007	FY 2008	FY 2009							
COTS	3.292	2.086	0.200	0.200	0.000	0.000	0.000							

A. Mission Description and Budget Item Justification:

The Commercial-off-the-Shelf (COTS) program is new for the JRP. Its purpose is to create a pool of small, mobile robots that will be made available on loan to government agencies, laboratories and universities. The goal of COTS is to assist agencies in defining their requirements, modifying their operational practices, and to make more appropriate acquisitions of unmanned systems. The robots that populate the pool will be COTS systems currently available from several manufacturers. The evaluations and experiments conducted with COTS robots will provide valuable feedback for future small robot developments. In requesting the loan of small robots from COTS, priority will go to Department of Defense, Homeland Security, and Emergency Response users. Where appropriate, COTS systems will be supplemented with unique developmental technologies to address emerging operational and programmatic requirements, for example, extensions to COTS systems in support of OEF/OIF.

B. Accomplishments/Planned Program

	FY 2003	FY 2004	FY 2005
Accomplishment/Effort/Subtotal Cost	3.292	0.000	0.000
RDT&E Articles Quantity * (as applicable)			

- Accomplishments for FY 2003 include:
 - o Robotic Systems Pool Chartered; Tri-Service Management Board established to provide guidance and vet requests for support.
 - o Robotic Systems Pool Standard Operating Procedures approved by JRP Managers.
 - o Loans made to the following organizations:
 - Joint Project Office Unmanned Ground Vehicle Systems
 - Navy EOD Mobile Unit Three
 - US Army 82nd Airborne
 - US Army Infantry Schools Command

- US Army Corps of Engineers
- Center for Robot Assisted Search and Rescue (CRASAR)
- San Diego Metro Arson Strike Team
- Las Vegas Metropolitan Police Department
- o Supported research completed at SPAWAR Systems Center San Diego on ground robot RF communications and data to determine optimum frequency and bandwidth for operations.
- o Collected, organized, and posted user feedback to on-line website.
- o Provided training for US Army, US Navy, San Diego County Sheriff, San Diego Metro Arson Strike Team, and Las Vegas Metropolitan Police Department SWAT.
- o Responded to 55 requests for robot loans and operational support.
- o Procurement of 15 new robotic systems and support equipment including fiber-optic spoolers, operator control units, and spares. (iRobot)
- o Development/procurement and rapid equipment fielding of four chemical/radiation/gas sensor suites for small robotic systems. (iRobot)
- o Enhancements to the (BBN) Ad Hoc Networking Radios used in small robotic systems including:
 - A new driver for the Cisco 802.11b card (with diversity antennas).
 - A study of power requirements for the ad hoc networking radios.
 - A power distribution/charging circuit for the radio.
 - A link-quality/connectivity graphic visualization program for the ad hoc network.
 - A centralized relay brick deployment program.
- o Development/procurement of a miniature perimeter surveillance radar that is less than half the size of the current model (PSRS) and detects human-sized intruders with 360 degrees of horizontal coverage and up to a range of 100m. The delivered system operates standalone or as payload component on man-portable UGS/backpackable robots with applications for force protection and remote sensing. Since its primary sensor is based on dual-use obstacle avoidance technology for the automotive industry (e.g. tractor trailers), the estimated per unit cost in production will be a fraction of the current model. (STS)
- o Development/procurement of a miniature stereo, vision-based obstacle detection and collision avoidance sensor used for small mobile robot navigation. This sensor will be used on a variety of small robots to aide in autonomous mobility to enhance the effectiveness of small mobile robots. (JPL)
- o Development/procurement of a novel unmanned ground vehicle with configurable/adaptable mobility modes. (ACEi)

- o Development of advanced small mobile robot autonomous navigation capabilities. Allows for autonomous mobility using high-resolution sensors such as LASERs. The software has been transferred to COTS small robots. (INEEL)
- o Development of an interface to the GOTS Common Geospatial Navigation Toolkit (COGENT) that allows NIMA Digital Nautical Charts to be displayed by other software application programs. This interface will be used in robotic operator control units. (SPAWAR Systems Center Charleston)

	FY 2003	FY 2004	FY 2005
Accomplishment/Effort/Subtotal			
Cost	0.000	0.200	0.200
RDT&E Articles Quantity * (as			
applicable)			

- Plans for FY 2004-2005 include:
 - o Procure off-the-shelf small robots for loan to government agencies, laboratories, and universities. Several configurations will be procured. Payloads that offer additional capabilities to address emerging threats/needs will be pursued.
 - o Collection of performance data to provide feedback to developers for the improvement of COTS systems and technologies.
 - o Provide advice, maintenance, and training to the requesting agencies.
 - o Continue maintenance, upgrades, and support as required.

C. Other Program Funding Summary:

Not Applicable

D. Acquisition Strategy:

Not Applicable

E. Major Performers:

Not Applicable

Exhibit R-3 Cost Analysis (pa											Date:		February 2	004				
DEFENSE-WIDE			Program Elem	ent							COTS							
BUDGET ACTIVITY 4				PE 0603709	9D8Z													
Cost Categories	Contract	Performing		Total	20	003		2003		2004		2004	2005		2005	Cost To	Total	Target
(Tailor to WBS, or System/Item	Method &	Activity &			Cost		ward		Cost		Award		Cost	Award		Complete	Cost	Value of
Requirements)	Туре	Location		Cost		Da	ate				Date			Date				Contract
COTS System Procurement					3.2	292				1.186								
Ancilliary Hardware Development																		
Systems Engineering																		
Licenses																		
Tooling																		
GFE																		
Award Fees																		
Subtotal Product Development	t				3.2	292				1.186			0.000					
Development Support																		
Software Development																		
Training Development																		
Integrated Logistics Support										0.200			0.200					
Configuration Management																		
Technical Data																		
GFE																		
Subtotal Support	t				0.0	000				0.200			0.200					
Remarks:																		
1																		

	004	
Performing Total 2003 2004 2004 2005 2006 2006 2005 2006		
Performing Total 2003 2004 2004 2005 2006 2006 2005 2006		
Type Location Cost Date Date Date Date Date Date Date Dat	2005 Cost To Total Tar	rget
TRE	Award Complete Cost Va	lue of
TRE	Date Co.	ntract
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tital Verification Testing		
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]	Exh	ibit	R-	4, Sc	he	dule	Pr	ofile												Da	ate:	Feb	orua	ry 2	004				
Appropriation/	Bud	get .	Acti	ivity	7						Pr	ogı	ram l	Elei	nent	Nu	mbe	r an	d N	ame	;						Pr	ojec	t Nı	umb	er a	nd N	Vam	ne		
DEFENSE WII	DE I	RDT	[&E	E/B.	A . #	4					PI	Ξ 0	6037	09I	08Z	– Jo	int l	Rob	otic	s Pro	ogra	m					CO	OTS								
Fiscal Year		20	01			20	02			20	003			2	004			20	005			20	06			20	07			20	800			20	09	
Fiscal Year	1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4
Procure COTS Systems																																				
Perform Maintenance,																																				
Training Support & Upgrades																																				

R-4 Schedule Profile

Exhibit R-	4a, Schedule De	tail			Dat	te: February	2004							
Appropriation/Budget Activity DEFENSE WIDE RDT&E/B.A. #4	Program Eleme PE 0603709DZ			n	Project Number and Name COTS									
		FY 2001	FY 2002	FY20	003	FY2004	FY2005	FY2006	FY2007	FY2008				
Procure COTS Systems				1-4Q										
Maintenance, Training, Support				Cont.		Cont.	Cont.	Cont.						

R-4a Schedule Profile